Changed parameters:

* Configuration.h

#define BAUDRATE 115200

#define BAUD\_RATE\_GCODE

#define MOTHERBOARD BOARD\_BTT\_OCTOPUS\_V1\_1

#define CUSTOM\_MACHINE\_NAME "5Axis Printer"

#define LINEAR\_AXES 5

#define AXIS4\_ROTATES

#define AXIS5\_ROTATES

#define HEATER\_0\_MAXTEMP 250

#define BED\_MAXTEMP 80

#define DEFAULT\_Kp 20.07 //22.20

#define DEFAULT\_Ki 1.39 //1.08

#define DEFAULT\_Kd 72.64 //114.00

#define PIDTEMPBED

#define COREXY

#define X\_MIN\_ENDSTOP\_INVERTING true

#define Y\_MIN\_ENDSTOP\_INVERTING true

#define Z\_MIN\_ENDSTOP\_INVERTING true

#define X\_DRIVER\_TYPE TMC2209

#define DEFAULT\_AXIS\_STEPS\_PER\_UNIT { 80, 80, 400 , 45 , 54, 400 }

#define DEFAULT\_MAX\_FEEDRATE { 300, 300, 50 , 300 , 300, 25 }

#define DEFAULT\_MAX\_ACCELERATION { 2000, 2000, 500, 1500, 1500, 500 }

#define CLASSIC\_JERK

#define S\_CURVE\_ACCELERATION

#define SENSORLESS\_PROBING

#define INVERT\_Z\_DIR true

#define INVERT\_I\_DIR true

#define INVERT\_E0\_DIR true

#define X\_BED\_SIZE 220

#define Y\_BED\_SIZE 220

#define I\_MIN\_POS -100 // EC : unconment it

#define I\_MAX\_POS 100 // EC : unconment it

#define J\_MIN\_POS -200 // EC : unconment it

#define J\_MAX\_POS 200 // EC : unconment it

#define DEBUG\_LEVELING\_FEATURE

#define MANUAL\_I\_HOME\_POS 0

#define MANUAL\_J\_HOME\_POS 0

#define HOMING\_FEEDRATE\_MM\_M { (50\*60), (50\*60), (4\*60), (4\*60), (4\*60)}

#define FAN\_SOFT\_PWM

* Configuration\_adv.h

#define USE\_CONTROLLER\_FAN

#define CONTROLLER\_FAN\_PIN PD12

#define CONTROLLERFAN\_SPEED\_MIN 50

#define CONTROLLERFAN\_SPEED\_ACTIVE 200

#define CONTROLLERFAN\_SPEED\_IDLE 50

#define CONTROLLERFAN\_IDLE\_TIME 60

#define FAN\_KICKSTART\_TIME 100

#define E0\_AUTO\_FAN\_PIN PA8

#define SENSORLESS\_BACKOFF\_MM { 2, 2, 0, 0, 0 }

#define HOMING\_BUMP\_MM { 0, 0, 2, 0, 0 }

#define HOMING\_BUMP\_DIVISOR { 2, 2, 4, 4, 4 }

#define QUICK\_HOME

#define QUICK\_HOME\_ALL\_NON\_Z\_AXES

#define HOME\_Y\_BEFORE\_X

#define CHOPPER\_TIMING\_X CHOPPER\_TIMING

#define CHOPPER\_TIMING\_Y CHOPPER\_TIMING

#define CHOPPER\_TIMING\_Z CHOPPER\_TIMING // For Z Axes (override below)

#define CHOPPER\_TIMING\_Z2 CHOPPER\_TIMING\_Z

#define CHOPPER\_TIMING\_I CHOPPER\_09STEP\_24V

#define CHOPPER\_TIMING\_J CHOPPER\_TIMING // For J Axis

#define CHOPPER\_TIMING\_E CHOPPER\_TIMING

#define MONITOR\_DRIVER\_STATUS

#define I\_STALL\_SENSITIVITY 8

#define J\_STALL\_SENSITIVITY 8

#define IMPROVE\_HOMING\_RELIABILITY

#define TMC\_HOME\_PHASE { 896, 896, 896, 896, 896 }

#define TMC\_DEBUG